

A Study of C-Reducible Finsler Space

With Special Cases

Dr. Pooja S. Saxena, Dr. Puneet Swaroop, Er. Swati Swaroop

Abstract

The notion of C-reducible Finsler Space has been introduced by M.Matsumoto(1972).The object of the paper is to study different types of generalized C-reducible Finsler spaces and also to study the properties of hypersurfaces immersed in C-reducible Finsler space.I have also worked out for T-conditions of Finsler space & show that the tensor T_{ijkh} vanishes if & only if the tensor T_{ijkl} vanishes for semi C-reducible Finsler spaces under certain conditions.

Keywords: Finsler Space, C-reducible, Quasi C-reducible, Semi C-reducible Finsler Space

1. Introduction

Let α and β be two independent functions given by $\alpha(=\alpha(x,y))=(a_{ij}(x) y^i y^j)^{1/2}$, $\beta(=\beta(x,y))=(b_{ij}(x)y^i y^j)^{1/2}$, ($y^i = dx^i$), $i, j= 1, \dots, N$, where $a_{ij}(x)$, $b_{ij}(x)$ are components of symmetric tensor fields of (0,2)-type, depending on the position x alone. Then we obtain an $N (\geq 2)$ -dimensional Finsler space F^N with a metric $L= L(\alpha(x,y), \beta(x,y))$, where $L(\alpha, \beta)$ is a positively homogeneous function of degree 1 with respect to two valuable α and β . **Definition:**

A non-Riemannian Finsler space is called generalized C-reducible, if the Cartan torsion tensor C_{ijk} is written in the form

$$C_{ijk} = P_{ij} Q_k + P_{jk} Q_i + P_{ki} Q_j$$

It is noted that quasi-C-reducible, semi-C-reducible or C-reducible Finsler spaces are special examples of generalized C-reducible Finsler spaces.

Differentiating $L = L(\alpha, \beta)$ by y^i, y^j and then y^k successively, it follows from $\hat{\partial}_i \alpha = \alpha^{-1} a_{i0}$, $\hat{\partial}_i \beta = \beta^{-1} b_{i0}$ that the normalized supporting element l_i , the angular metric tensor h_{ij} and the torsion tensor C_{ijk} are respectively given by

$$(1.1) \quad l_i = A a_{i0} + B b_{i0},$$

$$(1.2) \quad h_{ij} = L \{A a_{ij} + B b_{ij} + A_1 a_{i0} a_{j0} + A_2 (a_{i0} b_{j0} + a_{j0} b_{i0}) + B_2 b_{i0} b_{j0}\},$$

$$(1.3) \quad C_{ijk} = S_{(ijk)} \{pa_{ij}a_{ko} + q(a_{ij}b_{ko} + b_{ij}a_{ko}) + rb_{ij}b_{ko} \\ + (s/3) a_{io}a_{jo}a_{ko} + ta_{io}a_{jo}b_{ko} + ua_{io}b_{jo}b_{ko} + (v/3) b_{io}b_{jo}b_{ko}\}/2$$

where we put

$$\left\{ \begin{array}{l} A = L_{\alpha} \alpha^{-1}, \quad B = L_{\beta} \beta^{-1}, \\ A_1 = (L_{\alpha\alpha} - L_{\alpha} \alpha^{-1}) \alpha^{-2}, \quad A_2 = L_{\alpha\beta} \alpha^{-1} \beta^{-1}, \quad B_2 = (L_{\beta\beta} - L_{\beta} \beta^{-1}) \beta^{-2}, \\ A_{11} = (L_{\alpha\alpha\alpha} - 3L_{\alpha\alpha} \alpha^{-1} + 3L_{\alpha} \alpha^{-2}) \alpha^{-3}, \\ A_{12} = (L_{\alpha\alpha\beta} - L_{\alpha\beta} \alpha^{-1}) \alpha^{-2} \beta^{-1}, \\ A_{22} = (L_{\alpha\alpha\beta} - L_{\alpha\beta} \beta^{-1}) \alpha^{-1} \beta^{-2} \\ B_{22} = (L_{\beta\beta\beta} - 3L_{\beta\beta} \beta^{-1} + 3L_{\beta} \beta^{-2}) \beta^{-3} \\ \\ p = A^2 + LA_1, \quad q = AB + LA_2, \quad r = B^2 = B^2 + LB_2, \\ s = 3AA_1 + LA_{11}, \quad t = BA_1 + 2AA_2 + LA_{12}, \\ u = AB_2 + 2BA_2 + LA_{22}, \quad v = 3BB_2 + LB_{22}. \end{array} \right.$$

Here it is noted that the following identities hold

$$(1.5) \quad \left\{ \begin{array}{l} A\alpha^2 + B\beta^2 = L, \quad A_1\alpha^2 + A_2\beta^2 = -A, \quad A_2\alpha^2 + B_2\beta^2 = -B, \\ A_{11}\alpha^2 + A_{12}\beta^2 = -3A_1, \quad A_{12}\alpha^2 + A_{22}\beta^2 = -3A_2, \\ A_{22}\alpha^2 + B_{22}\beta^2 = -3B_2, \quad p\alpha^2 + q\beta^2 = 0, \quad q\alpha^2 + r\beta^2 = 0 \\ s\alpha^2 + t\beta^2 = -2p, \quad t\alpha^2 + u\beta^2 = -2q, \quad u\alpha^2 + v\beta^2 = -2r \end{array} \right.$$

Then we easily have

Proposition 1.1 :

The scalar q (or equivalently p, r) of the space F^N which is non-Riemannian does not vanish identically.

In virtue of above identities in (1.5) equation (1.3) is reduced to

$$(1.6) \quad C_{ijk} = P_{ij} Q_k + P_{jk} Q_i + P_{ki} Q_j,$$

where we put

$$P_{ij} = \alpha^{-2} \beta^{-2} \{-q(\beta^2 a_{ij} - \alpha^2 b_{ij}) + (s/3) \alpha^2 a_{io} a_{jo} + (1/6) (t\alpha^2 + u\beta^2) (a_{io} b_{jo} + a_{jo} b_{io}) - (v/3) \beta^2 b_{io} b_{jo}\} / 2,$$

$$Q_i = \beta^2 a_{io} - \alpha^2 b_{io}$$

and $P_{io} = Q_o = 0$ hold.

2. C-reducible Finsler Spaces :

In this section, we shall deal with the C-reducible Finsler Spaces which are defined by M. Matsumoto [2].

Definition :

An n (≥ 3)-dimensional Finsler Space F^n is called C-reducible if the $h(h\nu)$ -torsion tensor C_{ijk} is written in the form

$$(2.1) \quad C_{ijk} = (h_{ij} C_k + h_{jk} C_i + h_{ki} C_j) / (n+1).$$

Theorem 2.1 :

An n (≥ 3)-dimensional Finsler space is C-reducible if and only if the following equation is satisfied:

$$(2.2) \quad C^2 = 3c^2 / (n+1),$$

where $C^2 = C_{ijk} C^{ijk}$ and $c^2 = C_i C^i$.

Proof :

Using $C_{ijk} h^{jk} = C_i$ and $h_{ij} C^j = C_i$

we have

$$\begin{aligned} & [C_{ijk} - (C_i h_{jk} + C_j h_{ki} + C_k h_{ij}) / (n+1)] [C^{ijk} - (C^i h^{jk} + C^j h^{ki} + C^k h^{ij}) / (n+1)] \\ & = C^2 - 3c^2 / (n+1) \end{aligned}$$

Hence the theorem is proved.

Theorem 2.2 :

An $n (\geq 3)$ -dimensional Finsler space F^n is C -reducible if and only if the following equation is satisfied.

$$(2.3) \quad S_{hijk} = [c^2 (h_{kh}h_{ij} - h_{hj}h_{ik}) + C_h C_k h_{ij} \\ + C_i C_j h_{hk} - C_h C_j h_{ik} - C_i C_k h_{hj}] / (n+1)^2$$

Proof :

Assume that F^n is C -reducible. Then, it is known that (2.3) is satisfied [3]. Conversely, assume that (2.3) is satisfied. Then we have

$$C_{hkr} C_{ij}^r - C_{hjr} C_{ik}^r = [c^2 (h_{hk}h_{ij} - h_{hj}h_{ik}) + C_h C_k h_{ij} + C_i C_j h_{hk} \\ - C_h C_j h_{ik} - C_i C_k h_{hj}] / (n+1)^2$$

Contraction of this by $g^{hj}g^{ik}$ leads us to $C^2 - c^2 = - (n-2) c^2 / (n+1)$

Hence we have $C^2 = 3c^2 / (n+1)$.

By Theorem 2.1, F^n is C -reducible.

3. Quasi-C-reducibility :

Let M^n be an n -dimensional Finsler space with the fundamental function $L(x,y)$, the metric tensor g_{ij} , the angular metric tensor $h_{ij} = g_{ij} - l_i l_j$ ($l_i = \partial L / \partial y^i$) and the (h) hv-torsion tensor C_{ijk} . We assume that the torsion vector $C_i = g^{jk} C_{ijk}$ has non-zero length C and the dimension n is greater than two. Then, for instance, the v-covariant derivative of a tensor K_{ij} is denoted by $K_{ij|k}$ and the indicatization of K_{ij} by ${}^l(K_{ij}) = K_{rs} h_i^r h_j^s$.

We are concerned with some special forms of C_{ijk} . First of all, it is well known that C_{ijk} in any two-dimensional Finsler space is written in the form

$$(3.1) \quad C_{ijk} = C_i C_j C_k / C^2$$

Definition 1 :

A Finsler space is called C_2 -like, if the (h) hv-torsion tensor C_{ijk} is written in the form (3.1).

Definition 2 :

A Finsler space is called semi-C-reducible, if C_{ijk} is written in the form

$$(3.2) \quad C_{ijk} = [p/(n+1)] (h_{ij} C_k + h_{jk} C_i + h_{ki} C_j) + (q/C^2) C_i C_j C_k.$$

In the definition of semi-C-reducibility we do not assume that neither p nor q vanishes [5] so that semi-C-reducibility can include C-reducibility and C2-likeness. Finally, we give the definition of quasi-C-reducibility which was proposed by M. Matsumoto [4] .

Definition 4.

A Finsler space is called quasi-C-reducible, if C_{ijk} is written in the form

$$(3.3) \quad C_{ijk} = A_{ij} C_k + A_{jk} C_i + A_{ki} C_j,$$

where A_{ij} is a symmetric and indicatric tensor.

It is immediately seen that quasi-C-reducibility is a generalization of semi-C-reducibility.

Contracting (3.4) by g^{jk} , we obtain

$$(3.4) \quad A_{ik} C^k = \mu C_i,$$

where $\mu = (1-A)/2$ and $A = A_{jk} g^{jk}$. From (3.1), (2.1) and (3.3), when M^n is C-reducible, $A_{ij} = h_{ij}/(n+1)$. And when M^n is C2-like, $A_{ij} = C_i C_j / 3C^2$. The converses of these statements are true apparently and from (3.4) we have $\mu=1/(n+1)$ and $\mu = 1/3$ respectively.

4. Hypersurfaces of a C-reducible Finsler Space

Consider a non –Riemannian hypersurface F_{n-1} of F_n ($n \geq 4$), characterized by the equation $x^i = x^i(u^\alpha)$. The fundamental tensor of F_{n-1}

$$g_{\alpha\beta}(u, \dot{u}) = g_{ij}(x, \dot{x}) B_\alpha^i B_\beta^j \quad (4.1)$$

$$\text{where } \hat{\wedge}_{\alpha\beta} = g_{\gamma\delta} (B_\alpha^i = \frac{\partial x^i}{\partial u^\alpha}$$

A calculation based on the well known relation

$$C_{\alpha\beta\gamma} = C_{ijk} B_\alpha^i B_\beta^j B_\gamma^k \quad (4.2)$$

Above equations and the facts

$$h_{\alpha\beta} = g_{\alpha\beta} - l_{\alpha} l_{\beta}, l_{\alpha} = B_{\alpha}^i l_i \quad h_{\alpha\beta} = g_{\alpha\beta} - l_{\alpha} l_{\beta}, l_{\alpha} = B_{\alpha}^i l_i \quad \text{gives}$$

$$C_{\alpha\beta\gamma} = h_{\alpha\beta} C_{\gamma} + h_{\beta\gamma} C_{\alpha} + h_{\alpha\gamma} C_{\beta} \quad (4.3)$$

Where

$$C_{\alpha} = C_i B_{\alpha}^i = \frac{g^{\beta\gamma} C_{\alpha\beta\gamma}}{n}$$

This proves the following:

Theorem 4.1—A hypersurface of a C-reducible Finsler space is a C- reducible Finsler space. The difference between the intrinsic and induced connection parameters $\hat{\Gamma}_{\beta\gamma}^{\alpha}$ and $\Gamma_{\beta\gamma}^{*\alpha}$ of a hypersurface has been obtained by Rund(1965). If the space F_n is c- reducible then this difference tensor $\hat{\Delta}_{\alpha\beta}^{\delta} = g_{\gamma\delta} (\hat{\Gamma}_{\alpha\beta}^{\delta} - \Gamma_{\alpha\beta}^{*\delta})$ reduces to the form:

$$\hat{\Delta}_{\alpha\beta\gamma} = \rho \left[h_{\beta\gamma} (\Omega_{\alpha 0} - C_{\alpha} \Omega_{00}) + h_{\alpha\gamma} (\Omega_{\beta 0} - C_{\beta} \Omega_{00}) - h_{\alpha\beta} (\Omega_{\gamma 0} + C_{\gamma} \Omega_{00}) \right] \quad (4.4)$$

Where $\Omega_{\alpha 0} = 0$ $\Omega_{\alpha\beta}$ are the components of second fundamental tensor of F_{n-1} , $\rho = C_i N^i$ and N^i are the components of the unit vector normal to the Hypersurface. This equation proves the following:

Theorem 4.2—The necessary and sufficient condition that intrinsic and induced connection parameters of a hypersurface of a C-reducible Finsler space be equal is that either $\Omega_{\alpha 0} = 0$ or the vector C_i is tangential to the surface.

5. On the Indicatized Tensor T_{ijkl} :

Let M^n be an n -dimensional Finsler space with the fundamental function $L(x,y)$ where x is a point of M^n and y is an element of support. If we denote $g_{ij}(x,y)$ the components of the metric tensor derived from $L(x,y)$, the angular metric tensor h_{ij} and (h) $h\nu$ -torsion tensor C_{ijk} are given as

$$h_{ij} = g_{ij} - l_i l_j, C_{ijk} = \frac{1}{2} \partial g_{ij} / \partial y^k \text{ respectively,}$$

where $l_i = \partial L / \partial y^i$ in the normalized element of support. Then, for instance, the ν -covariant derivative of the tensor K_j^i and the indicatization of the tensor K_{ijk} are defined respectively as follows :

$$(5.1) \quad K_j^i|_k = \partial K_j^i / \partial y^k + K_j^r C_{rk}^i - K_r^i C_{jk}^r,$$

$$(5.2) \quad {}^l(K_{ijk}) = K_{rst} h_i^r h_j^s h_k^t,$$

where

$$h_i^r = g^{rj} h_{ji} = \delta_i^r - l^r l_i, \quad l^i = g^{ij} l_j$$

We define the indicatrized tensors of $C_{ijk|_h}$ and $S_{ijkh|_l}$ by the following equations and denote these tensors by T_{ijkh} and T_{ijkhl} respectively :

$$(5.3) \quad T_{ijkh} = {}^l(C_{ijk|_h}) \\ = C_{ijk|_h} + L^{-1} (C_{ijk} l_h + C_{hjk} l_i + C_{ihk} l_j + C_{ijh} l_k),$$

$$(5.4) \quad T_{ijkhl} = {}^l(S_{ijkh|_l}) \\ = S_{ijkh|_l} + L^{-1} (2S_{ijkh} l_l + S_{ijkh} l_i + S_{ilkh} l_j + S_{ijlh} l_k + S_{ijkl} l_h).$$

From the identities

$$(5.5) \quad S_{ijkh} = C_{ihm} C_{jk}^m - C_{ikm} C_{jh}^m,$$

We find that

$$(5.6) \quad S_{ijkh|_l} = C_{ihm|_l} C_{jk}^m + C_{ihm} C_{jk}^m|_l - C_{ikm|_l} C_{jh}^m - C_{ikm} C_{jh}^m|_l$$

Indicatrizing the above equation using the properties of indicatrization [1], we obtain

$$(5.7) \quad T_{ijkhl} = T_{ihml} C_{jk}^m + T_{jkml} C_{ih}^m - T_{ikml} C_{jh}^m - T_{jhml} C_{ik}^m.$$

It follows from (5.7) that

Theorem 5.1 :

If the tensor T_{ijkh} vanishes, then the tensor T_{ijkhl} also vanishes.

Theorem 5.2 :

Let F_{ijkhl} and G_{ijkhl} be defined as follows :

$$\begin{aligned}
 (5.8) \quad F_{ijkl} &= 2 (h_{ih} h_{jk} - h_{ik} h_{jh}) C_l + (h_{lh} h_{jk} - h_{lk} h_{jh}) C_i \\
 &+ (h_{ih} h_{lk} - h_{ik} h_{lh}) C_j + (h_{ih} h_{jl} - h_{il} h_{jh}) C_k \\
 &+ (h_{il} h_{jk} - h_{ik} h_{jl}) C_h, \\
 G_{ijkl} &= (h_{ih} C_j C_k + h_{jk} C_i C_h - h_{ik} C_j C_h - h_{jh} C_i C_k) C_l.
 \end{aligned}$$

Then the scalars s and t satisfying the equation

$$(5.9) \quad sF_{ijkl} + tG_{ijkl} = 0$$

must be equal to zero, provided that M^n is of dimension $n > 3$ and C is non-zero.

Proof:

Contracting (7.9) with g^{ih} and C^l , we obtain

$$C^2 \{2(n-1)s + C^2 t\} h_{jk} + (n-3) (2s + C^2 t) C_j C_k = 0.$$

From the above equation we have

$$2(n-1)s + C^2 t = 0 \text{ and } 2s + C^2 t = 0, \text{ which give } s = t = 0$$

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